

Pro-face

PS-2000B Series

RAS-API Reference Manual

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1 Operation Environment

This document explains the use of Dynamic Link Libraries (API-DLL) to access RAS features from an application running on a PS-2000B Series unit.

The API-DLLs explained in this document are PSB_Ioc.dll and PSB_Ras.dll.

PSB_Ioc.dll is used by applications to access the following System Monitor/RAS features.

- Driver Version information
- System Monitor feature status
- Read out (Get) various monitoring parameters (voltage, fan, temperature)
- System Monitor current data (voltage, fan, temperature)
- Watchdog parameters
- Alarm processing
- General input processing
- Reset (of PS-B unit)
- Event handling
- Get Soft Mirror status^{*1}

PSB_Ras.dll is used to access the Remote RAS feature's Common Memory API-DLL. PSB_Ras.dll is used by applications to access the following features.

- Reads from common memory
- Writes to common memory

2 Compatible Operating Systems and Languages

The API-DLLs are compatible with the following OS types and languages.

| OS | Languages |
|-------------------------|--|
| Microsoft® Windows®2000 | Microsoft® Visual C |
| Microsoft® Windows®XP | Microsoft® Visual C++® Microsoft® Visual Basic® |

*1 Only when using the Soft Mirror (PL-SM900)

3 Required Files

The following files are required when using PSB_Ioc.dlls. Each language requires its own set of files.

| Language | File Name | Description |
|--------------|--------------|--|
| Visual C | PSB_Iocif.h | Driver interface definition "include" file |
| | PSB_Ioc.lib | Library definition file |
| | PSB_Ioc.dll | Dynamic link library file |
| Visual C++ | PSB_Iocif.h | Driver interface definition "include" file |
| | PSB_Iocall.h | CPSB_Iocall class definition "include" file ^{*1} |
| | PSB_Ioctl.h | CPSB_Ioctl class definition "include" file |
| | PSB_Ioc.lib | Library definition file |
| | PSB_Ioc.dll | Dynamic link library file |
| | Sm.h | Soft Mirror definition file (Only when using Soft Mirror) |
| Visual Basic | PSB_Ioc.bas | Driver interface definition file |
| | PSB_Ioc.lib | Library definition file |
| | PSB_Ioc.dll | Dynamic link library file |

*1 "#include" header files should be "included" in the following order.

PSB_Iocall.h is automatically included, and does not need to be directly designated.
#include PSB_Iocif.h
#include PSB_Ioctl.h

The following files are required when using PSB_Ras.dlls. Each language requires its own set of files.

| Language | File Name | Description |
|--------------|-------------|--|
| Visual C | PSB_Ras.h | Driver interface definition "include" file |
| | PSB_Ras.LIB | Library definition file |
| | PSB_Ras.dll | Dynamic link Library file |
| Visual C++ | PSB_Ras.h | Driver interface definition "include" file |
| | PSB_Ras.LIB | Library definition file |
| | PSB_Ras.dll | Dynamic link Library file |
| Visual Basic | PSB_Ras.LIB | Library definition file |
| | PSB_Ras.dll | Dynamic link Library file |

MEMO

Each file is located in the [Proface] folder's [PSBApi] folder.
Place the files that you need in one of the following folders,
or in the same folder as your application.

| OS | Location |
|--------------------------|---------------------|
| Microsoft® Windows® 2000 | C:\Winnt\System32 |
| Microsoft® Windows® XP | C:\Windows\System32 |

4 Class Contents

4.1 CPSB_Ioctl Class

This class is used to set the parameters for device driver access using CPSB_Ioctl class.

| Key Word | Type | Variable name | Description |
|----------|--------|---------------|----------------------|
| public | HANDLE | m_Drvhandle | Device driver handle |

4.2 CPSB_Ioctl Class

This uses the parameters set in CPSB_Ioctl and, calls up DeviceIOControl (Driver Access function).

However, since this class succeeds CPSB_Ioctl, it cannot be used directly.

| Key Word | Type | Variable Name | Description |
|----------|--------------|---------------|--|
| public | HANDLE | m_h | Device driver handle |
| public | LONG | m_long | Control code for action to perform |
| public | void * | m_ibp | Input data buffer address |
| public | ULONG | m_ibsize | Input data buffer size |
| public | void * | m(obp) | Output data buffer address |
| public | ULONG | m_obsizes | Output data buffer size |
| public | DWORD | m_retsizes | Address for actual no. of output bytes |
| public | LPOVERLAPPED | m_ovlp | Address of overlap design |

4.3 CPSB_SmiIoctl Class

This class is used to set the parameters for device driver access using CPSB_SmiIoctl class.

| Key Word | Type | Variable name | Description |
|----------|--------|---------------|----------------------|
| public | HANDLE | m_Drvhandle | Device driver handle |

5 Function Specifications

5.1 Visual C Functions

PSB_Loc.dll Functions

| Function Name | Description |
|-------------------|--|
| InitIoctl | Creates the CPSB_Ioctl object |
| EndIoctl | Destroys the CPSB_Ioctl object |
| GetDrvHandle | Gets the driver handle |
| CloseDrvHandle | Destroys the driver handle |
| GetDrvVersion | Gets the driver version |
| GetDrvVersionEx | Gets the hardware type and driver version |
| GetMonitorSetup | Gets the monitoring enabled/disabled setting |
| GetVoltParam | Gets the voltage monitoring parameter |
| GetCurrentVolt | Gets the current voltage value |
| GetFanParam | Gets the fan monitoring parameter |
| GetCurrentFan | Gets the current fan value |
| GetTempParam | Gets the temperature monitoring parameter |
| GetCurrentTemp | Gets the current temperature value |
| SetWdtCounter | Sets the watchdog timer counter |
| GetWdtCounter | Gets the watchdog timer counter |
| SetWdtDOutMask | Sets warning masking in case of watchdog timer timeout |
| GetWdtDOutMask | Gets warning masking in case of watchdog timer timeout |
| StartWdt | Starts the watchdog timer |
| StopWdt | Stops the watchdog timer |
| RestartWdt | Restarts the watchdog timer |
| GetWdtStatus | Gets the watchdog timer operation status |
| SetDOut | Sets universal output |
| GetDOut | Gets universal output |
| GetDIn | Gets universal input |
| ClearDIn | Clear the universal input latched status |
| SetDInMask | Sets universal input masking |
| GetDInMask | Gets universal input masking |
| SetResetMask | Sets reset-masking |
| GetResetMask | Gets reset-masking |
| GetEvent | Gets the error event |
| ClearEvent | Clear the error event |
| GetWdtTimeout | Gets the timeout status of the watchdog timer |
| ClearWdtTimeout | Clear the timeout status of the watchdog timer |
| SetWdtResetMask | Sets the ResetMask of the watchdog timer |
| GetWdtResetMask | Gets the ResetMask of the watchdog timer |
| GetSmiDrvHandle | Gets the soft mirror driver handle |
| CloseSmiDrvHandle | Destroys the soft mirror driver handle |
| GetSmiAryStatus | Gets the soft mirror array status |
| GetSmeDevStatus | Gets the soft mirror device status |

PSB_Ras.dll Functions

| Function Name | Description |
|-----------------|--------------------------|
| PsbDevWordWrite | Writes to common memory |
| PsbDevWordRead | Reads from common memory |

5.2 Visual C Programming Cautions

When using API-DLLs, it is important to first create the driver object and get the device handle. When you finish using the API-DLL, you will need to destroy both the device handle and the driver object. Refer to the following example when developing your programs.

MEMO

Only when using PsbDevWordWrite and PsbDevWordRead, it is not necessary to create/destroy the driver object and the device handle.

Sample Program

```
// Example of using an API-DLL
// Variable language
BOOL bRet;
int iRet;
HANDLE hDrv;
// Create the driver object and get the device handle
// Create CPSB_Ioctl object
InitIoctl();
iRet = GetDrvHandle(&Drv);
.

.

.

// Output to DOUT3
bRet = SetDOut(PORT_DOUT3, OUTPUT_ON);

.

.

// Application shut-down processing
// Destroy both the device handle and the driver object
bRet = CloseDrvHandle();
EndIoctl();
```

5.3 Visual C Function Specifications (Details)

InitIoctl

Call Format

void WINAPI InitIoctl(void)

Return Value

None

Arguments

None

Processing

Creates a CPL_Ioctl object. The object is not destroyed until the EndIoctl function is called.

Example

InitIoctl();

EndIoctl

Call Format

```
void WINAPI EndIoctl(void)
```

Return Value

None

Arguments

None

Processing

Destroys CPSB_Ioctl object created using the InitIoctl function.

Example

```
EndIoctl();
```

GetDrvHandle

Call Format

```
int WINAPI GetDrvHandle(HANDLE *pHndl)
```

Return Value

0 Normal

1 Error

Arguments

(I/O)HANDLE *pHndl Pointer to the device driver handle

Processing

Gets the device driver handle to communicate with the device driver.

Example

```
int ret;  
HANDLE Hndl;  
ret = GetDrvHandle(&Hndl);
```

MEMO

Error (Return Value : 1) will result if the system monitor/RAS device driver is not operating.

CloseDrvHandle

Call Format

```
BOOL WINAPI CloseDrvHandle(void)
```

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

Destroys the device driver handle created using the GetDrvHandle function.

Example

```
BOOL ret;  
ret = CloseDrvHandle();
```

GetDrvVersion

Call Format

BOOL WINAPI GetDrvVersion(int *pMajor, int *pMinor)

Return Value

TRUE Normal

FALSE Error

Arguments

| | |
|-------------------|--------------------------------|
| (I/O) int *pMajor | Pointer to version information |
|-------------------|--------------------------------|

| | |
|-------------------|--------------------------------|
| (I/O) int *pMinor | Pointer to version information |
|-------------------|--------------------------------|

Processing

Gets the driver's version information

Example

```
BOOL ret;
int Major, Minor;
ret = GetDrvVersion(&Major, &Minor);
```

MEMO

For example, if the version is 1.00, then you will get

Major : 1 (decimal)

Minor : 00 (decimal).

GetDrvVersionEx

Call Format

BOOL WINAPI GetDrvVersionEx(int *pProduct, int *pMajor, int *pMinor)

Return Value

TRUE Normal

FALSE Error

Arguments

| | |
|---------------------|--------------------------|
| (I/O) int *pProduct | Pointer to hardware type |
|---------------------|--------------------------|

| | |
|-------------------|--------------------------------|
| (I/O) int *pMajor | Pointer to version information |
|-------------------|--------------------------------|

| | |
|-------------------|--------------------------------|
| (I/O) int *pMinor | Pointer to version information |
|-------------------|--------------------------------|

Processing

Gets the hardware type and driver version.

Example

```
BOOL ret;
int Product, Major, Minor;
ret = GetDrvVersionEx(&Product, &Major, &Minor);
```

MEMO

For example, if the H/W type is PS-2000B and the version is 1.00, then you will get

Product : 1 (decimal)

Major : 1 (decimal)

Minor : 00 (decimal)

GetMonitorSetup

Call Format

```
BOOL WINAPI GetMonitorSetup(int Selector, int *pSetup)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|---------------------|--------------------|
| MONITOR_VOLT_CPU | CPUVoltage |
| MONITOR_VOLT_P33 | +3.3V |
| MONITOR_VOLT_P50 | +5.0V |
| MONITOR_VOLT_P12 | +12V |
| MONITOR_VOLT_M12 | -12V |
| MONITOR_VOLT_VIT | CPUVoltage2 |
| MONITOR_TEMP_SYSTEM | System temperature |
| MONITOR_TEMP_CPU | CPU temperature |
| MONITOR_FAN_CPU | CPU fan |
| MONITOR_FAN_POWER | POWER fan |

(I/O) int *pSetup

Pointer to Data

0 : Disable

1 : Enable

Processing

Gets the current monitoring status (enabled/disabled).

Example

```
BOOL ret;
```

```
int Setup;
```

```
// Gets the CPU core voltage setup status.
```

```
ret = GetMonitorSetup(MONITOR_VOLT_CPU, &Setup);
```

GetVoltParam

Call Format

```
BOOL WINAPI GetVoltParam(int Selector, int *pULimit, int *pLLimit)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|------------------|-------------|
| MONITOR_VOLT_CPU | CPU voltage |
|------------------|-------------|

| | |
|------------------|-------|
| MONITOR_VOLT_P33 | +3.3V |
|------------------|-------|

| | |
|------------------|-------|
| MONITOR_VOLT_P50 | +5.0V |
|------------------|-------|

| | |
|------------------|------|
| MONITOR_VOLT_P12 | +12V |
|------------------|------|

| | |
|------------------|------|
| MONITOR_VOLT_M12 | -12V |
|------------------|------|

| | |
|------------------|--------------|
| MONITOR_VOLT_VIT | CPU voltage2 |
|------------------|--------------|

(I/O) int *pULimit Pointer to upper-limit voltage value (Unit: mV)

(I/O) int *pLLimit Pointer to lower-limit voltage value (Unit: mV)

Processing

Gets the voltage monitoring parameter.

Example

```
BOOL ret;
```

```
int ULimit, LLlimit;
```

```
// Gets the upper and lower-limit values of the CPU core voltage.
```

```
ret = GetVoltParam(MONITOR_VOLT_CPU, &ULimit, &LLlimit);
```

MEMO

The data taken from this function is shown in mV units.

Perform the following conversion use in (Volt) units:

Data in Volt unit = Data in mV unit /1000

GetCurrentVolt

Call Format

```
BOOL WINAPI GetCurrentVolt(int Selector, int *pData)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|------------------|--------------|
| MONITOR_VOLT_CPU | CPU voltage |
| MONITOR_VOLT_P33 | +3.3V |
| MONITOR_VOLT_P50 | +5.0V |
| MONITOR_VOLT_P12 | +12V |
| MONITOR_VOLT_M12 | -12V |
| MONITOR_VOLT_VIT | CPU voltage2 |

(I/O) int *pData

Pointer to the voltage value (unit: mV)

Processing

Gets the current voltage value.

Example

```
BOOL ret;
int Data;
// Gets the CPU core voltage value.
ret = GetCurrentVolt(MONITOR_VOLT_CPU, &Data);
```

MEMO

The data taken from this function is shown in mV units.

Perform the following conversion for use in (Volt) units:

$$\text{Data in Volt unit} = \text{Data in mV unit} / 1000$$

GetFanParam

Call Format

```
BOOL WINAPI GetFanParam(int Selector, int *pLLimit)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|-------------------|-----------|
| MONITOR_FAN_CPU | CPU fan |
| MONITOR_FAN_POWER | POWER fan |

(I/O) int *pLLimit

Pointer to the lower-limit fan rotation speed (Unit: RPM)
(RPM : Revolutions Per Minute)

Processing

Gets the fan monitoring parameter.

Example

```
BOOL ret;
int LLimit;
// Gets the lower-limit CPU fan rotation speed.
ret = GetFanParam(MONITOR_FAN_CPU, &LLimit);
```

GetCurrentFan

Call Format

BOOL WINAPI GetCurrentFan(int Selector, int *pData)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameter

MONITOR_FAN_CPU CPU fan

MONITOR_FAN_POWER POWER fan

(I/O) int *pData

Pointer to the fan rotation speed (Unit: RPM)

(RPM : Revolutions Per Minute)

Processing

Gets the current fan rotational speed.

Example

```
BOOL ret;
int Data;
// Gets the CPU fan rotational speed.
ret = GetCurrentFan(MONITOR_FAN_CPU, &Data);
```

GetTempParam

Call Format

BOOL WINAPI GetTempParam(int Selector, int *pULimit)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

MONITOR_TEMP_CPU CPU temperature

MONITOR_TEMP_SYSTEM System temperature

(I/O) int *pULimit

Pointer to the upper-limit temperature (Unit:Degrees Celsius).

Processing

Gets the temperature monitoring parameter.

Example

```
BOOL ret;
int ULimit;
// Gets the CPU temperature upper-limit value.
ret = GetTempParam(MONITOR_TEMP_CPU, &ULimit);
```

GetCurrentTemp

Call Format

```
BOOL WINAPI GetCurrentTemp(int Selector, int *pData)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

MONITOR_TEMP_CPU CPU temperature

MONITOR_TEMP_SYSTEM System temperature

(I/O) int *pData Pointer to the temperature (Unit:Degrees Celsius).

Processing

Gets the current temperature value.

Example

```
BOOL ret;
```

```
int Data;
```

```
// Gets the CPU temperature value.
```

```
ret = GetCurrentTemp(MONITOR_TEMP_CPU, &Data);
```

SetWdtCounter

Call Format

```
BOOL WINAPI SetWdtCounter(int Counter)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Counter

Sets to the watchdog timer's initial counter
value(5 to 255)(Unit:Seconds)

Processing

Sets the current watchdog timer's initial counter value.

Example

```
BOOL ret;
```

```
// Sets the current watchdog timer's initial counter value to 10 sec.
```

```
ret = SetWdtCounter(10);
```

GetWdtCounter

Call Format

BOOL WINAPI GetWdtCounter(int *pCounter)

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pCounter Pointer to the watchdog timer's initial counter value (Unit:Seconds).

Processing

Gets the current watchdog timer's initial counter value.

Example

```
BOOL ret;
int Counter;
// Gets the current watchdog timer's initial counter value.
ret = GetWdtCounter(&Counter);
```

SetWdtDOutMask

Call Format

BOOL WINAPI SetWdtDOutMask(int Selector, int Mask)

Return Value

TRUE Normal

FALSE Error

Arguments

| | Setting Item |
|------------------|------------------|
| (I) int Selector | PORT_DOUT0 DOUT0 |
| | PORT_DOUT1 DOUT1 |
| | PORT_DOUT2 DOUT2 |
| | PORT_DOUT3 DOUT3 |

| | Masking Information |
|--------------|---------------------------|
| (I) int Mask | MASK_OFF Masking disabled |
| | MASK_ON Masking enabled |

Processing

Sets mask for the RAS port used for Watchdog Timer Timeout output.

Example

```
BOOL ret;
// Mask the RAS port's DOUT0.
ret = SetWdtDOutMask(PORT_DOUT0, MASK_ON);
```

GetWdtDOutMask

Call Format

```
BOOL WINAPI GetWdtDOutMask(int Selector, int *pMask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

| | Setting Item | |
|------------|--------------|--|
| PORT_DOUT0 | DOUT0 | |
| PORT_DOUT1 | DOUT1 | |
| PORT_DOUT2 | DOUT2 | |
| PORT_DOUT3 | DOUT3 | |

(I/O) int *pMask

| | Pointer to Masking Information | |
|----------|--------------------------------|--|
| MASK_OFF | Masking disabled | |
| MASK_ON | Masking enabled | |

Processing

Gets the masking information used for RAS port when watchdog timer time-out occurs.

Example

```
BOOL ret;
```

```
int Mask;
```

```
// Gets the masking information for the DOUT0 of RAS port.
```

```
ret = GetWdtDOutMask(PORT_DOUT0, &Mask);
```

StartWdt

Call Format

```
BOOL WINAPI StartWdt(void)
```

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

Starts watchdog timer count down.

Example

```
BOOL ret;
```

```
ret = StartWdt();
```

StopWdt

Call Format

BOOL WINAPI StopWdt(void)

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

Stops watchdog timer countdown.

Example

BOOL ret;

ret = StopWdt();

RestartWdt

Call Format

BOOL WINAPI RestartWdt(void)

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

This feature resets the Watchdog timer that is currently counting (down) to its initial value, and restarts the countdown.

Example

BOOL ret;

ret = RestartWdt();

MEMO

RestartWdt can only be used after the StartWdt countdown has started. If RestartWdt is used after the timeout, it should be after ClearWdtTimeout has used to clear the timeout condition and after StartWdt has started the countdown.

GetWdtStatus

Call Format

BOOL WINAPI GetWdtStatus(int *pRunFlag)

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pRunFlag

Pointer to the watchdog timer operation status

WATCHDOG_STOP Stopped

WATCHDOG_COUNTDOWN Countdown in progress

Processing

Gets the watchdog timer's operation status.

Example

BOOL ret;

int RunFlag;

ret = GetWdtStatus(&RunFlag);

SetDOut

Call Format

BOOL WINAPI SetDOut(int Selector, int Dout)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

| | Setting Item | |
|------------|--------------|--|
| PORT_DOUT0 | DOUT0 | |
| PORT_DOUT1 | DOUT1 | |
| PORT_DOUT2 | DOUT2 | |
| PORT_DOUT3 | DOUT3 | |

(I) int Dout

| | Output Status | |
|------------|---------------|--|
| OUTPUT_OFF | Output OFF | |
| OUTPUT_ON | Output ON | |

Processing

Sets the Common Output port (DOUT) output data.

Example

```
BOOL ret;  
ret = SetDOut(PORT_DOUT0, OUTPUT_ON);
```

GetDOut

Call Format

BOOL WINAPI GetDOut(int Selector, int *pDout)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

| | Setting Item | |
|------------|--------------|--|
| PORT_DOUT0 | DOUT0 | |
| PORT_DOUT1 | DOUT1 | |
| PORT_DOUT2 | DOUT2 | |
| PORT_DOUT3 | DOUT3 | |

(I/O) int *pDout

| | Pointer to Output Status | |
|------------|--------------------------|--|
| OUTPUT_OFF | Output OFF | |
| OUTPUT_ON | Output ON | |

Processing

Gets the Common Output port (DOUT) output data.

Example

```
BOOL ret;  
int Dout;  
ret = GetDOut(PORT_DOUT0, &Dout);
```

GetDIn

Call Format

BOOL WINAPI GetDIn(int Selector, int *pDin)

Return Value

TRUE Normal

FALSE Error

Arguments

| | | |
|------------------|-------------------------|-----------|
| (I) int Selector | Setting Item | |
| | POR T_DIN0 | DIN0 |
| | POR T_DIN1 | DIN1 |
| | POR T_DIN2 | DIN2 |
| | POR T_DIN3 | DIN3 |
| (I/O) int *pDin | Pointer to Input Status | |
| | INPUT_OFF | Input OFF |
| | INPUT_ON | Input ON |

Processing

Gets Input information.

Example

```
BOOL ret;
int Din;
ret = GetDIn(PORT_DIN0, &Din);
```

ClearDIn

Call Format

BOOL WINAPI ClearDIn(int Selector)

Return Value

TRUE Normal

FALSE Error

Arguments

| | | |
|------------------|--------------|------|
| (I) int Selector | Setting Item | |
| | POR T_DIN0 | DIN0 |
| | POR T_DIN1 | DIN1 |
| | POR T_DIN2 | DIN2 |
| | POR T_DIN3 | DIN3 |

Processing

Releases the Common Input port (DIN) input status.

Example

```
BOOL ret;
ret=ClearDIn(PORT_DIN0);
```

SetDInMask

Call Format

```
BOOL WINAPI SetDInMask(int Selector, int Mask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

| | Setting Item |
|-----------|--------------|
| PORT_DIN0 | DIN0 |
| PORT_DIN1 | DIN1 |
| PORT_DIN2 | DIN2 |
| PORT_DIN3 | DIN3 |

(I) int Mask

| | Masking Information |
|----------|---------------------|
| MASK_ON | Masking enabled |
| MASK_OFF | Masking disabled |

Processing

Sets the Common Input Port (DIN) input status.

Example

```
BOOL ret;
```

```
ret = SetDInMask(PORT_DIN0, MASK_OFF);
```

GetDInMask

Call Format

```
BOOL WINAPI GetDInMask(int Selector, int *pMask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

| | Setting Item |
|-----------|--------------|
| PORT_DIN0 | DIN0 |
| PORT_DIN1 | DIN1 |
| PORT_DIN2 | DIN2 |
| PORT_DIN3 | DIN3 |

(I/O) int *pMask

| | Pointer to Masking Information |
|----------|--------------------------------|
| MASK_ON | Masking enabled |
| MASK_OFF | Masking disabled |

Processing

Gets the masking information for the designated port (DIN)

Example

```
BOOL ret;
```

```
int Mask;
```

```
ret = GetDInMask(PORT_DIN0, &Mask);
```

SetResetMask

Call Format

BOOL WINAPI SetResetMask(int Mask)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Mask Masking Information

 MASK_ON Masking enabled

 MASK_OFF Masking disabled

Processing

Sets the reset port's mask data.

Example

BOOL ret;

```
ret = SetResetMask(MASK_OFF);
```

GetResetMask

Call Format

BOOL WINAPI GetResetMask(int *pMask)

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pMask Pointer to Masking Information

 MASK_ON Masking disabled

 MASK_OFF Masking enabled

Processing

Gets the current reset-masking information.

Example

BOOL ret;

int Mask;

```
ret = GetResetMask(&Mask);
```

GetEvent

Call Format

```
BOOL WINAPI GetEvent(int Selector, int *pRasevnt)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|---------------------|------------------------------------|
| EVENT_VOLT_CPU | CPU voltage |
| EVENT_VOLT_P33 | +3.3V |
| EVENT_VOLT_P50 | +5V |
| EVENT_VOLT_P12 | +12V |
| EVENT_VOLT_M12 | -12V |
| EVENT_VOLT_VIT | CPU voltage2 |
| EVENT_FAN_CPU | CPU fan |
| EVENT_FAN_POWER | POWER fan |
| EVENT_TEMP_SYSTEM | System temperature |
| EVENT_TEMP_CPU | CPU temperature |
| EVENT_DIN0 | DIN0 |
| EVENT_DIN1 | DIN1 |
| EVENT_DIN2 | DIN2 |
| EVENT_DIN3 | DIN3 |
| EVENT_WDT_TIMEOUT | Watchdog Timer |
| (I/O) int *pRasevnt | Pointer to Error Event Information |
| ERROR_EVENT_ON | With error event |
| ERROR_EVENT_OFF | Without error event |

Processing

Gets the error event.

Example

```
BOOL ret;
```

```
int Rasevnt;
```

```
ret=GetEvent(EVENT_DIN0,&Rasevnt);
```

ClearEvent

Call Format

BOOL WINAPI ClearEvent(int Selector)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|-------------------|--------------------|
| EVENT_VOLT_CPU | CPU voltage |
| EVENT_VOLT_P33 | +3.3V |
| EVENT_VOLT_P50 | +5V |
| EVENT_VOLT_P12 | +12V |
| EVENT_VOLT_M12 | -12V |
| EVENT_VOLT_VIT | CPU voltage2 |
| EVENT_FAN_CPU | CPU fan |
| EVENT_FAN_POWER | POWER fan |
| EVENT_TEMP_SYSTEM | System temperature |
| EVENT_TEMP_CPU | CPU temperature |
| EVENT_DIN0 | DIN0 |
| EVENT_DIN1 | DIN1 |
| EVENT_DIN2 | DIN2 |
| EVENT_DIN3 | DIN3 |
| EVENT_WDT_TIMEOUT | Watchdog Timer |

Processing

Cancels the error event.

Example

BOOL ret;

ret = ClearEvent(EVENT_DIN0);

GetWdtTimeout

Call Format

BOOL WINAPI GetWdtTimeout(int *pTimebuf)

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pTimebuf

Pointer to Watchdog Timeout Status

| | |
|-------------|--------------------------|
| TIMEOUT_OK | Timeout has not occurred |
| TIMEOUT_ERR | Timeout has occurred |

Processing

Gets watchdog timeout status.

Example

BOOL ret;

int Timebuf;

ret = GetWdtTimeout(&Timebuf);

ClearWdtTimeout

Call Format

BOOL WINAPI ClearWdtTimeout(void)

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

Clears the watchdog timeout status.

Example

BOOL ret;

```
ret = ClearWdtTimeout();
```

SetWdtResetMask

Call Format

BOOL WINAPI SetWdtResetMask(int Mask)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Mask Masking Information

 MASK_OFF Masking disabled

 MASK_ON Masking enabled

Processing

Sets the H/W reset mask used at WDT timeout.

Example

BOOL ret;

```
ret = SetWdtResetMask(MASK_ON);
```

GetWdtResetMask

Call Format

BOOL WINAPI GetWdtResetMask(int *pMask)

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pMask Pointer to Masking Information

 MASK_OFF Masking disabled

 MASK_ON Masking enabled

Processing

Gets the H/W reset mask data used at WDT timeout.

Example

BOOL ret;

int Mask;

```
ret = GetWdtResetMask(&Mask);
```

PsbDevWordWrite

Call Format

long PsbDevWordWrite(long Addr, long wData)

Return Value

0 Normal

Other than 0 Error

Arguments

(I) long Addr Write memory word address

(I) long wData Write data (0 to 65535)

Processing

Writes to common memory.

Example

// Writes data 255 to address 255.

long ret;

ret = PsbDevWordWrite(255, 255);

PsbDevWordRead

Call Format

long PsbDevWordRead(long Addr, long *wData)

Return Value

0 Normal

Other than 0 Error

Arguments

(I) long Addr Read memory word address

(I/O) long *wData Pointer to Read data (0 to 65535)

Processing

Reads from common memory.

Example

// Reads address 255's data.

long ret;

long wData;

ret = PsbDevWordRead(255, &wData);

GetSmiDrvHandle

Call Format

```
int WINAPI GetSmiDrvHandle(void)
```

Return Value

0 Normal

1 Error

Arguments

None

Processing

Gets the Soft Mirror driver handle.

Example

```
// Gets the handle.
```

```
int ret;
```

```
ret=GetSmiDrvHandle();
```

MEMO

Error (Return Value : 1) will result if the soft mirror device driver is not operating.

CloseSmiDrvHandle

Call Format

```
BOOL WINAPI CloseSmiDrvHandle(void)
```

Return Value

TRUE Normal

FALES Error

Arguments

None

Processing

Destroys the Soft Mirror driver handle.

Example

```
// Destroys the handle.
```

```
BOOL ret;
```

```
ret=CloseSmiDrvHandle();
```

GetSmiAryStatus

Call Format

```
BOOL WINAPI GetSmiAryHandle(int *pStatus)
```

Return Value

TRUE Normal

FALES Error

Arguments

| | | |
|--------------------|-----------------------------|---------------------------|
| (I/O) int *pStatus | Pointor to mirroring status | |
| | ARYSTAT_GOOD | Normal |
| | ARYSTAT_UNCONFIG | Under Configuration |
| | ARYSTAT_REBUILD | Rebuild |
| | ARYSTAT_REDUCE | Reduced |
| | ARYSTAT_DEAD | Destroy the mirror status |

Processing

Gets the Soft Mirror's mirroring status.

Example

```
BOOL ret;
```

```
int Status;
```

```
ret=GetSmiAryStatus();
```

GetSmiDevStatus

Call Format

```
BOOL WINAPI GetSmiDevStatus(int Id, int *pType, int *pStatus)
```

Return Value

| | |
|-------|--------|
| TRUE | Normal |
| FALSE | Error |

Arguments

| | | |
|--------------------|------------------|---------------|
| (I) int Id | Device ID | |
| | 0 : Master HDD | |
| | 1 : Slave HDD | |
| (I/O) int *pType | Device Type | |
| | ATADEVICE | ATA device |
| | ATAPIDEVICE | CD-ROMdrive |
| | NODEVICE | Not connected |
| (I/O) int *pStatus | Device Status | |
| | DEVSTAT_GOOD | Normal |
| | DEVSTAT_NOTEXIST | Not connected |
| | DEVSTAT_BROKEN | Broken |

Processing

Gets the soft mirror's device status.

Example

```
//Gets the master HDD's device status
BOOL ret;
int Type, Status;
ret = GetSmiDevStatus(0, &Type, &Status);
```

Memo

5.4 Visual C++ Functions

PSB_Loc.dll Functions

| Function Name | Description |
|-------------------|---|
| GetDrvHandle | Gets the driver handle |
| CloseDrvHandle | Destroys the driver handle |
| GetDrvVersion | Gets the driver version |
| GetDrvVersionEx | Gets the hardware type and driver version |
| GetMonitorSetup | Gets the monitoring enabled/disabled setting |
| GetVoltParam | Gets the voltage monitoring parameter |
| GetCurrentVolt | Gets the current voltage value |
| GetFanParam | Gets the fan monitoring parameter |
| GetCurrentFan | Gets the current fan value |
| GetTempParam | Gets the temperature monitoring parameter |
| GetCurrentTemp | Gets the current temperature value |
| SetWdtCounter | Sets the watchdog timer counter |
| GetWdtCounter | Gets the watchdog timer counter |
| SetWdtDOutMask | Sets the warning masking in case of watchdog timer time-out |
| GetWdtDOutMask | Gets the warning masking in case of watchdog timer time-out |
| StartWdt | Starts the watchdog timer |
| StopWdt | Stops the watchdog timer |
| RestartWdt | Restarts the watchdog timer |
| GetWdtStatus | Gets the watchdog timer operation status |
| SetDOut | Sets universal output |
| GetDOut | Gets universal output |
| GetDIn | Gets universal input |
| ClearDIn | Clears the universal input latched status |
| SetDInMask | Sets universal input masking |
| GetDInMask | Gets universal input masking |
| SetResetMask | Sets reset-masking |
| GetResetMask | Gets reset-masking |
| GetEvent | Gets the error event |
| ClearEvent | Clears the error event |
| GetWdtTimeout | Gets watchdog timeout status |
| ClearWdtTimeout | Clears the watchdog timeout status |
| SetWdtResetMask | Sets the RestMask of the watchdog timer |
| GetWdtResetMask | Gets the ResetMask of the watchdog timer |
| GetSmiDrvHandle | Gets the soft mirror driver handle |
| CloseSmiDrvHandle | Destroys the soft mirror driver handle |
| GetSmiAryStatus | Gets the soft mirror array status |
| GetSmiDevStatus | Gets the soft mirror device status |

PSB_Ras.dll Functions

| Function Name | Description |
|-----------------|--------------------------|
| PsbDevWordWrite | Writes to common memory |
| PsbDevWordRead | Reads from common memory |

5.5 Visual C++ Programming Cautions

When using API-DLLs, it is important to first get the device handle. When you finish using the API-DLL, you will need to destroy the device handle object. Refer to the following example when developing your programs.

MEMO

Only when using PsbDevWordWrite and PsbDevWordRead, it is not necessary to create/destroy the driver object and the device handle.

Sample Program

```
// Example of using an API-DLL
// Variable language
BOOL bRet;
int iRet;
// Get the device handle
CPSB_Ioctl m_Ioc;
iRet = m_Ioc.GetDrvHandle();

.

.

.

// Output to DOUT0
bRet=m_Ioc.SetDOut(PORT_DOUT0,OUTPUT_ON);

.

.

.

// Destroy the device handle
bRet = m_Ioc.CloseDrvHandle();
```

5.6 Visual C++ Function Specifications (Details)

GetDrvHandle

Call Format

int GetDrvHandle(HANDLE *pHndl) or int GetDrvHandle()

Return Value

0 Normal

1 Error

Arguments

(I/O) HANDLE *pHndl Pointer to the device driver handle

Processing

Gets the device driver handle to communicate with the device driver.

Example1

int ret;

HANDLE Hndl;

ret = ::GetDrvHandle(&Hndl);

Example2

CPSB_Ioctl m_Ioctl;

int ret;

ret = m_Ioctl.GetDrvHandle();

MEMO

Error (Return Value : 1) will result if the System Monitor/RAS Device Driver is not running.

CloseDrvHandle

Call Format

BOOL CloseDrvHandle(void)

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

Destroys the device driver handle created using the GetDrvHandle function.

Example1

```
BOOL ret;
ret = ::CloseDrvHandle();
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
ret = m_Ioctl.CloseDrvHandle();
```

GetDrvVersion

Call Format

BOOL GetDrvVersion(int *pMajor, int *pMinor)

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pMajor Pointer to version information

(I/O) int *pMinor Pointer to version information

Processing

Gets the driver's version information.

Example1

```
BOOL ret;
int Major, Minor;
ret = ::GetDrvVersion(&Major, &Minor);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int Major, Minor;
ret = m_Ioctl.GetDrvVersion(&Major, &Minor);
```

MEMO

For example, if the version is 1.00, then you will get

Major : 1 (decimal)

Minor : 00 (decimal)

GetDrvVersionEx

Call Format

```
BOOL GetDrvVersionEx(int *pProduct, int *pMajor, int *pMinor)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pProduct Pointer to Hardware type

(I/O) int *pMajor Pointer to version information

(I/O) int *pMinor Pointer to version information

Processing

Gets the hardware type and driver's version information.

Example1

```
BOOL ret;
```

```
int Product, Major, Minor;
```

```
ret = ::GetDrvVersionEx(&Product, &Major, &Minor);
```

Example2

```
CPSB_Ioctl m_Ioctl;
```

```
BOOL ret;
```

```
int Product, Major, Minor;
```

```
ret = m_Ioctl.GetDrvVersionEx(&Product, &Major, &Minor);
```

MEMO

For example, if the H/W type is PS-2000B and the version is 1.00, then you will get

Product : 1 (decimal)

Major : 1 (decimal)

Minor : 00 (decimal)

GetMonitorSetup

Call Format

```
BOOL GetMonitorSetup(int Selector, int *pSetup)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|---------------------|--------------------|
| MONITOR_VOLT_CPU | CPU voltage |
| MONITOR_VOLT_P33 | +3.3V |
| MONITOR_VOLT_P50 | +5.0V |
| MONITOR_VOLT_P12 | +12V |
| MONITOR_VOLT_M12 | -12V |
| MONITOR_VOLT_VIT | CPU voltage2 |
| MONITOR_TEMP_SYSTEM | System temperature |
| MONITOR_TEMP_CPU | CPU temperature |
| MONITOR_FAN_CPU | CPU fan |
| MONITOR_FAN_POWER | POWER fan |

(I/O) int *pSetup

Pointer to gotten Data

0 : Disable

1 : Enable

Processing

Gets the current monitoring enabled/disabled status.

Example1

```
BOOL ret;
int Setup;
// Gets the CPU core voltage setup status.
ret = ::GetMonitorSetup(MONITOR_VOLT_CPU, &Setup);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int Setup;
// Gets the CPU core voltage setup status.
ret=m_Ioctl.GetMonitorSetup(MONITOR_VOLT_CPU,&Setup);
```

GetVoltParam

Call Format

```
BOOL GetVoltParam(int Selector, int *pULimit, int *pLLimit)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|------------------|--------------|
| MONITOR_VOLT_CPU | CPU voltage |
| MONITOR_VOLT_P33 | +3.3V |
| MONITOR_VOLT_P50 | +5.0V |
| MONITOR_VOLT_P12 | +12V |
| MONITOR_VOLT_M12 | -12V |
| MONITOR_VOLT_VIT | CPU voltage2 |

(I/O) int *pULimit Pointer to upper-limit voltage value (Unit: mV)

(I/O) int *pLLimit Pointer to lower-limit voltage value (Unit: mV)

Processing

Gets the voltage monitoring parameter.

Example1

```
BOOL ret;
int ULimit, LLimit;
// Gets the upper and lower-limit values of the CPU core voltage.
ret = ::GetVoltParam(MONITOR_VOLT_CPU, &ULimit, &LLimit);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int ULimit, LLimit;
// Gets the upper and lower-limit values of the CPU core voltage.
ret = m_Ioctl.GetVoltParam(MONITOR_VOLT_CPU, &ULimit, &LLimit);
```

MEMO

The data taken from this function is shown in mV units.

Perform the following conversion for use in (Volt) units :

$$\text{Data in Volt unit} = \text{Data in mV unit} / 1000$$

GetCurrentVolt

Call Format

```
BOOL GetCurrentVolt(int Selector, int *pData)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|------------------|--------------|
| MONITOR_VOLT_CPU | CPU voltage |
| MONITOR_VOLT_P33 | +3.3V |
| MONITOR_VOLT_P50 | +5.0V |
| MONITOR_VOLT_P12 | +12V |
| MONITOR_VOLT_M12 | -12V |
| MONITOR_VOLT_VIT | CPU voltage2 |

(I/O) int *pData Pointer to the voltage value (Unit: mV)

Processing

Gets the current voltage value.

Example1

```
BOOL ret;
int Data;
// Gets the CPU core voltage value.
ret = ::GetCurrentVolt(MONITOR_VOLT_CPU, &Data);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int Data;
// Gets the CPU core voltage value.
ret = m_Ioctl.GetCurrentVolt(MONITOR_VOLT_CPU, &Data);
```

MEMO

The data taken from this function is shown in mV units.

Perform the following conversion for use in (Volt) units :

$$\text{Data in Volt unit} = \text{Data in mV unit} / 1000$$

GetFanParam

Call Format

```
BOOL GetFanParam(int Selector, int *pLLimit)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

MONITOR_FAN_CPU CPU fan

MONITOR_FAN_POWER POWER fan

(I/O) int *pLLimit

Pointer to the lower-limit fan rotation speed (Unit: RPM)

(RPM : Revolutions Per Minute)

Processing

Gets the fan monitoring parameter.

Example1

```
BOOL ret;  
int LLimit;  
// Gets the lower-limit CPU fan rotational speed.  
ret = ::GetFanParam(MONITOR_FAN_CPU, &LLimit);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
int LLimit;  
// Gets the lower-limit CPU fan rotational speed.  
ret = m_Ioctl.GetFanParam(MONITOR_FAN_CPU, &LLimit);
```

GetCurrentFan

Call Format

```
BOOL GetCurrentFan(int Selector, int *pData)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

MONITOR_FAN_CPU CPU fan

MONITOR_FAN_POWER POWER fan

(I/O) int *pData

Pointer to the fan rotation speed (Unit: RPM)

(RPM : Revolutions Per Minute)

Processing

Gets the current fan rotation speed.

Example1

```
BOOL ret;  
int Data;  
// Gets the CPU fan rotation speed.  
ret = ::GetCurrentFan(MONITOR_FAN_CPU, &Data);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
int Data;  
// Gets the CPU fan rotation speed.  
ret = m_Ioctl.GetCurrentFan(MONITOR_FAN_CPU, &Data);
```

GetTempParam

Call Format

BOOL GetTempParam(int Selector, int *pULimit)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

MONITOR_TEMP_CPU CPU temperature

MONITOR_TEMP_SYSTEM System temperature

(I/O) int *pULimit Pointer to the upper-limit temperature (Unit: Degrees Celsius)

Processing

Gets the temperature monitoring parameter.

Example1

```
BOOL ret;
int ULimit;
// Gets the CPU temperature upper-limit value.
ret = ::GetTempParam(MONITOR_TEMP_CPU, &ULimit);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int ULimit;
// Gets the CPU temperature upper-limit value.
ret = m_Ioctl.GetTempParam(MONITOR_TEMP_CPU, &ULimit);
```

GetCurrentTemp

Call Format

BOOL GetCurrentTemp(int Selector, int *pData)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

MONITOR_TEMP_CPU CPU temperature

MONITOR_TEMP_SYSTEM System temperature

(I/O) int *pData Pointer to the temperature (Unit: Degrees Celsius)

Processing

Gets the current temperature value.

Example1

```
BOOL ret;
int Data;
// Gets the CPU temperature value.
ret = ::GetCurrentTemp(MONITOR_TEMP_CPU, &Data);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int Data;
// Gets the CPU temperature value.
ret = m_Ioctl.GetCurrentTemp(MONITOR_TEMP_CPU, &Data);
```

SetWdtCounter

Call Format

BOOL SetWdtCounter(int Counter)

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Counter Sets to the watchdog timer's initial counter value. (5 to255)(Unit: Seconds)

Processing

Sets the watchdog timers initial counter value.

Example1

```
BOOL ret;  
// Sets the watchdog timers initial counter value to 10.  
ret = ::SetWdtCounter(10);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
// Sets the watchdog timers initial counter value to 10.  
ret = m_Ioctl.SetWdtCounter(10);
```

GetWdtCounter

Call Format

BOOL GetWdtCounter(int *pCounter)

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pCounter Pointer to the watchdog timer's initial counter value. (Unit: Seconds)

Processing

Gets the current watchdog timer's initial counter value.

Example1

```
BOOL ret;  
int Counter;  
// Gets the current watchdog timer's initial counter value.  
ret = ::GetWdtCounter(&Counter);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
int Counter;  
// Gets the current watchdog timer's initial counter value.  
ret = m_Ioctl.GetWdtCounter(&Counter);
```

SetWdtDOutMask

Call Format

```
BOOL SetWdtDOutMask(int Selector, int Mask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

| | |
|------------------|---------------------------|
| (I) int Selector | Setting Item |
| | PORT_DOUT0 DOUT0 |
| | PORT_DOUT1 DOUT1 |
| | PORT_DOUT2 DOUT2 |
| | PORT_DOUT3 DOUT3 |
| (I) int Mask | Masking Information |
| | MASK_OFF Masking disabled |
| | MASK_ON Masking enabled |

Processing

Sets mask for the RAS port used for Watchdog Timer Timeout output.

Example1

```
BOOL ret;  
// Mask the RAS port's DOUT0.  
ret = ::SetWdtDOutMask(PORT_DOUT0, MASK_ON);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
// Mask the RAS port's DOUT0.  
ret = m_Ioctl.SetWdtDOutMask(PORT_DOUT0, MASK_ON);
```

GetWdtDOutMask

Call Format

```
BOOL GetWdtDOutMask(int Selector, int *pMask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

| | Setting Item | |
|------------|--------------|--|
| PORT_DOUT0 | DOUT0 | |
| PORT_DOUT1 | DOUT1 | |
| PORT_DOUT2 | DOUT2 | |
| PORT_DOUT3 | DOUT3 | |

(I/O) int *pMask

| | Pointer to Masking Information | |
|----------|--------------------------------|--|
| MASK_OFF | Masking disabled | |
| MASK_ON | Masking enabled | |

Processing

Gets the RAS port masking information that is created when a watchdog timer time-out occurs.

Example1

```
BOOL ret;  
int Mask;  
// Gets the DOUT0 of RAS port masking information.  
ret = ::GetWdtDOutMask(PORT_DOUT0, &Mask);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
int Mask;  
// Gets the DOUT0 of RAS port masking information.  
ret = m_Ioctl.GetWdtDOutMask(PORT_DOUT0, &Mask);
```

StartWdt

Call Format

```
BOOL StartWdt(void)
```

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

Starts watchdog timer countdown.

Example1

```
BOOL ret;  
ret = ::StartWdt();
```

Example2

```
CPSB_Ioctlm_Ioctl;  
BOOL ret;  
ret = m_Ioctl.StartWdt();
```

StopWdt

Call Format

```
BOOL StopWdt(void)
```

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

Stops watchdog timer countdown.

Example1

```
BOOL ret;
```

```
ret = ::StopWdt();
```

Example2

```
CPSB_Ioctl m_Ioctl;
```

```
BOOL ret;
```

```
ret = m_Ioctl.StopWdt();
```

RestartWdt

Call Format

```
BOOL RestartWdt(void)
```

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

This feature resets the Watchdog timer that is currently counting (down) to its initial value, and restarts the countdown.

Example1

```
BOOL ret;
```

```
ret = ::RestartWdt();
```

Example2

```
CPSB_Ioctl m_Ioctl;
```

```
BOOL ret;
```

```
ret = m_Ioctl.RestartWdt();
```

MEMO

RestartWdt can only be used after the StartWdt countdown has started. If RestartWdt is used after the timeout, it should be after ClearWdtTimeout has been used to clear the timeout condition and after StartWdt has started the countdown.

GetWdtStatus

Call Format

```
BOOL GetWdtStatus(int *pRunFlag)
```

Return Value

TRUE Normal

FALSE Error

Arguments

| | |
|---------------------|---|
| (I/O) int *pRunFlag | Pointer to Watchdog Timer Operation Status. |
| | WATCHDOG_STOP Stopped |
| | WATCHDOG_COUNTDOWN Countdown in progress |

Processing

Gets the watchdog timer's operation status.

Example1

```
BOOL ret;  
int RunFlag;  
ret = ::GetWdtStatus(&RunFlag);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
int RunFlag;  
ret = m_Ioctl.GetWdtStatus(&RunFlag);
```

SetDOut

Call Format

```
BOOL SetDOut(int Selector, int Dout)
```

Return Value

TRUE Normal

FALSE Error

Arguments

| | | |
|------------------|---------------|------------|
| (I) int Selector | Setting Item | |
| | PORT_DOUT0 | DOUT0 |
| | PORT_DOUT1 | DOUT1 |
| | PORT_DOUT2 | DOUT2 |
| | PORT_DOUT3 | DOUT3 |
| (I) int Dout | Output Status | |
| | OUTPUT_OFF | Output OFF |
| | OUTPUT_ON | Output ON |

Processing

Sets the Common Output port (DOUT) output data.

Example1

```
BOOL ret;  
ret=::SetDOut(PORT_DOUT0,OUTPUT_ON);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
ret = m_Ioctl.SetDOut(PORT_DOUT0, OUTPUT_ON);
```

GetDOut

Call Format

BOOL GetDOut(int Selector, int *pDout)

Return Value

TRUE Noromal

FALSE Error

Arguments

| | | |
|------------------|--------------------------|------------|
| (I) int Selector | Setting Item | |
| | POR T_DOUT0 | DOUT0 |
| | POR T_DOUT1 | DOUT1 |
| | POR T_DOUT2 | DOUT2 |
| | POR T_DOUT3 | DOUT3 |
| (I/O) int *pDout | Pointer to Output Status | |
| | OUTPUT_OFF | Output OFF |
| | OUTPUT_ON | Output ON |

Processing

Gets the Common Output port (DOUT) output data.

Example1

```
BOOL ret;
int Dout;
ret = ::GetDOut(PORT_DOUT0, &Dout);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int Dout;
ret = m_Ioctl.GetDOut(PORT_DOUT0, &Dout);
```

GetDIn

Call Format

BOOL GetDIn(int Selector, int *pDin)

Return Value

TRUE Normal

FALSE Error

Arguments

| | | |
|------------------|-------------------------|-----------|
| (I) int Selector | Setting Item | |
| | POR T_DIN0 | DIN0 |
| | POR T_DIN1 | DIN1 |
| | POR T_DIN2 | DIN2 |
| | POR T_DIN3 | DIN3 |
| (I/O) int *pDin | Pointer to Input Status | |
| | INPUT_OFF | Input OFF |
| | INPUT_ON | Input ON |

Processing

Gets the input status of the designated port (DIN).

Example1

```
BOOL ret;
int Din;
ret = ::GetDIn(PORT_DIN0, &Din);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int Din;
ret = m_Ioctl.GetDIn(PORT_DIN0, &Din);
```

ClearDIn

Call Format

```
BOOL ClearDIn(int Selector)
```

Return Value

TRUE Normal

FALSE Error

Arguments

| | | |
|------------------|--------------|------|
| (I) int Selector | Setting Item | |
| | PORT_DIN0 | DIN0 |
| | PORT_DIN1 | DIN1 |
| | PORT_DIN2 | DIN2 |
| | PORT_DIN3 | DIN3 |

Processing

Releases the Common Input port (DIN) input status.

Example1

```
BOOL ret;  
ret = ::ClearDIn(PORT_DIN0);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
ret = m_Ioctl.ClearDIn(PORT_DIN0);
```

SetDInMask

Call Format

```
BOOL SetDInMask(int Selector, int Mask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

| | | |
|------------------|---------------------|------------------|
| (I) int Selector | Setting Item | |
| | PORT_DIN0 | DIN0 |
| | PORT_DIN1 | DIN1 |
| | PORT_DIN2 | DIN2 |
| | PORT_DIN3 | DIN3 |
| (I) int Mask | Masking Information | |
| | MASK_ON | Masking enabled |
| | MASK_OFF | Masking disabled |

Processing

Sets the Common Input Port (DIN) input status.

Example1

```
BOOL ret;  
ret = ::SetDInMask(PORT_DIN0, MASK_OFF);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
ret = m_Ioctl.SetDInMask(PORT_DIN0, MASK_OFF);
```

GetDInMask

Call Format

BOOL GetDInMask(int Selector, int *pMask)

Return Value

TRUE Normal

FALSE Error

Arguments

| | | |
|------------------|--------------------------------|------------------|
| (I) int Selector | Setting Item | |
| | PORT_DIN0 | DIN0 |
| | PORT_DIN1 | DIN1 |
| | PORT_DIN2 | DIN2 |
| | PORT_DIN3 | DIN3 |
| (I/O) int *pMask | Pointer to Masking Information | |
| | MASK_ON | Masking enabled |
| | MASK_OFF | Masking disabled |

Processing

Gets the masking information for the designated port (DIN).

Example1

```
BOOL ret;
int Mask;
ret = ::GetDInMask(PORT_DIN0, &Mask);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int Mask;
ret = m_Ioctl.GetDInMask(PORT_DIN0, &Mask);
```

SetResetMask

Call Format

BOOL SetResetMask(int Mask)

Return Value

TRUE Normal

FALSE Error

Arguments

| | | |
|--------------|---------------------|------------------|
| (I) int Mask | Masking Information | |
| | MASK_ON | Masking enabled |
| | MASK_OFF | Masking disabled |

Processing

Sets the reset port's mask data.

Example1

```
BOOL ret;
ret = ::SetResetMask(MASK_OFF);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
ret = m_Ioctl.SetResetMask(MASK_OFF);
```

GetResetMask

Call Format

```
BOOL GetResetMask(int *pMask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

| | |
|------------------|--------------------------------|
| (I/O) int *pMask | Pointer to Masking Information |
| | MASK_ON Masking enabled |
| | MASK_OFF Masking disabled |

Processing

Gets the current reset-masking information.

Example1

```
BOOL ret;  
int Mask;  
ret = ::GetResetMask(&Mask);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
int Mask;  
ret = m_Ioctl.GetResetMask(&Mask);
```

GetEvent

Call Format

```
BOOL GetEvent(int Selector, int *pRasevnt)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|---------------------|------------------------------|
| EVENT_VOLT_CPU | CPU voltage |
| EVENT_VOLT_P33 | +3.3V |
| EVENT_VOLT_P50 | +5V |
| EVENT_VOLT_P12 | +12V |
| EVENT_VOLT_M12 | -12V |
| EVENT_VOLT_VIT | CPU voltage2 |
| EVENT_FAN_CPU | CPU fan |
| EVENT_FAN_POWER | POWER fan |
| EVENT_TEMP_SYSTEM | System temperature |
| EVENT_TEMP_CPU | CPU temperature |
| EVENT_DIN0 | DIN0 |
| EVENT_DIN1 | DIN1 |
| EVENT_DIN2 | DIN2 |
| EVENT_DIN3 | DIN3 |
| EVENT_WDT_TIMEOUT | Watchdog Timer |
| (I/O) int *pRasevnt | Pointer to Event Information |
| ERROR_EVENT_ON | With Event |
| ERROR_EVENT_OFF | Without Event |

Processing

Gets event information.

Example1

```
BOOL ret;
int Rasevent;
ret=::GetEvent(EVENT_DIN0,&Rasevent);
```

Example2

```
CPSB_Ioctl m_Ioctl;
BOOL ret;
int Rasevnt;
ret=m_Ioctl.GetEvent(EVENT_DIN0,&Rasevnt);
```

ClearEvent

Call Format

```
BOOL ClearEvent(int Selector)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Selector

Parameters

| | |
|-------------------|--------------------|
| EVENT_VOLT_CPU | CPU voltage |
| EVENT_VOLT_P33 | +3.3V |
| EVENT_VOLT_P50 | +5V |
| EVENT_VOLT_P12 | +12V |
| EVENT_VOLT_M12 | -12V |
| EVENT_VOLT_VIT | CPU voltage2 |
| EVENT_FAN_CPU | CPU fan |
| EVENT_FAN_POWER | POWER fan |
| EVENT_TEMP_SYSTEM | System temperature |
| EVENT_TEMP_CPU | CPU temperature |
| EVENT_DIN0 | DIN0 |
| EVENT_DIN1 | DIN1 |
| EVENT_DIN2 | DIN2 |
| EVENT_DIN3 | DIN3 |
| EVENT_WDT_TIMEOUT | Watchdog Timer |

Processing

Cancels the error event.

Example1

```
BOOL ret;  
ret = ::ClearEvent(EVENT_DIN0);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
ret = m_Ioctl.ClearEvent(EVENT_DIN0);
```

GetWdtTimeout

Call Format

BOOL GetWdtTimeout(int *pTimebuf)

Return Value

TRUE Normal

FALSE Error

Arguments

| | |
|---------------------|--|
| (I/O) int *pTimebuf | Pointer to Watchdog Status |
| | TIMEOUT_OK Timeout has not occurred |
| | TIMEOUT_ERR Timeout has occurred |

Processing

Gets watchdog timeout status.

Example1

```
BOOL ret;
int Timebuf;
ret = ::GetWdtTimeout(&Timebuf);
```

Example2

```
CPSB_Ioclt m_Ioclt;
BOOL ret;
int Timebuf;
ret = m_Ioclt.GetWdtTimeout(&Timebuf);
```

ClearWdtTimeout

Call Format

BOOL ClearWdtTimeout(void)

Return Value

TRUE Normal

FALSE Error

Arguments

None

Processing

Clears the watchdog timeout status.

Example1

```
BOOL ret;
ret = ::ClearWdtTimeout();
```

Example2

```
CPSB_Ioclt m_Ioclt;
BOOL ret;
ret = m_Ioclt.ClearWdtTimeout();
```

SetWdtResetMask

Call Format

```
BOOL SetWdtResetMask (int Mask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I) int Mask Masking Information

 MASK_OFF Masking disabled

 MASK_ON Masking enabled

Processing

Sets WDT Timeout H/W reset-masking.

Example1

```
BOOL ret;  
ret = ::SetWdtResetMask(MASK_ON);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
ret = m_Ioctl.SetWdtResetMask(MASK_ON);
```

GetWdtResetMask

Call Format

```
BOOL GetWdtResetMask(int *pMask)
```

Return Value

TRUE Normal

FALSE Error

Arguments

(I/O) int *pMask Pointer to Masking Information

 MASK_OFF Masking disabled

 MASK_ON Masking enabled

Processing

Gets the current WDT timeout H/W reset-masking information.

Example1

```
BOOL ret;  
int Mask;  
ret = ::GetWdtResetMask(&Mask);
```

Example2

```
CPSB_Ioctl m_Ioctl;  
BOOL ret;  
int Mask;  
ret = m_Ioctl.GetWdtResetMask(&Mask);
```

PsbDevWordWrite

Call Format

long PsbDevWordWrite(long Addr, long wData)

Return Value

0 Normal

Other than 0 Error

Arguments

(I) long Addr Write memory word address

(I) long wData Write data (0 to 65535)

Processing

Writes to common memory.

Example

// Writes data 255 to address 255.

long ret;

ret = PsbDevWordWrite(255, 255);

PsbDevWordRead

Call Format

long PsbDevWordRead(long Addr, long *wData)

Return Value

0 Normal

Other than 0 Error

Arguments

(I) long Addr Read memory word address

(I/O) long *wData Pointer to Read data (0 to 65535)

Processing

Reads from common memory.

Example

// Reads address 255's data.

long ret;

long wData;

ret = PsbDevWordRead(255, &wData);

GetSmiDrvHandle

Call Format

```
intGetSmiDrvHandle(void)
```

Return Value

0 Normal

1 Error

Arguments

None

Processing

Gets the soft mirror device driver handle.

Example 1

```
int ret;
```

```
ret=::GetSmiDrvHandle();
```

Example 2

```
CPSB_SmiIoctlm_SmiIoctl;
```

```
int ret;
```

```
ret=m_SmiIoctl.GetSmiDrvHandle();
```

MEMO

Error (Return Value : 1) will result if the soft mirror device driver is not operating.

CloseSmiDrvHandle

Call Format

```
BOOLCloseSmiDrvHandle(void)
```

Return Value

TRUE Normal

FALES Error

Arguments

None

Processing

Destroys the soft mirror device driver handle.

Example 1

```
BOOLret;
```

```
ret=::CloseSmiDrvHandle();
```

Example 2

```
CPSB_SmiIoctlm_SmiIoctl;
```

```
BOOLret;
```

```
ret=m_SmiIoctl.CloseSmiDrvHandle();
```

GetSmiAryStatus

Call Format

```
BOOL GetSmiAryStatus(int *pStatus)
```

Return Value

| | |
|------|--------|
| TRUE | Normal |
|------|--------|

| | |
|-------|-------|
| FALES | Error |
|-------|-------|

Arguments

| | |
|------------------|---|
| (I) int *pStatus | Pointor to the soft mirror's mirroring status |
| | ARYSTAT_GOOD Normal |
| | ARYSTAT_UNCONFIG Under configuration |
| | ARYSTAT_REBUILD Rebuild |
| | ARYSTAT_R EDUCED Reduced |
| | ARYSTAT_DEAD Destroys the mirror status |

Processing

Gets the soft mirror's mirroring status.

Example 1

```
BOOL ret;  
int Status  
ret=::GetSmiAryStatus(&Status);
```

Example 2

```
CPSB_SmiIoctlm_SmiIoctl;  
BOOL ret;  
int Status  
ret=m_SmiIoctl.GetSmiAryStatus(&Status);
```

GetSmiDevStatus

Call Format

```
BOOL GetSmiDevStatus(int ID, int *pType, int *pStatus)
```

Return Value

| | |
|-------|--------|
| TRUE | Normal |
| FALSE | Error |

Arguments

| | |
|--------------------|--|
| (I) int ID | Device ID 0 : Master HDD 1 : Slave HDD |
| (I/O) int *pType | pointer to the device type ATADEVICE ATA device ATAPIDEVICE CD-ROM NODEVICE Not connected |
| (I/O) int *pStatus | pointer to device status DEVSTAT_GOOD Normal DEVSTAT_NOTEXIST Not connected DEVSTAT_BROKEN Broken |

Processing

Gets the soft mirror device status.

Example 1

```
BOOL ret;  
int Type, Status  
ret=::GetSmiDrvStatus(0, &Type, &Status);
```

Example 2

```
CPSB_SmiIoctlm_SmiIoctl;  
int Type, Status  
ret=m_SmiIoctl.GetSmiDrvStatus(0, &Type, &Status);
```

5.7 Visual Basic Functions

PSB_loc.dll Functions

| Function Name | Description |
|-------------------|--|
| InitIoctl | Creates a CFT_Ioctl object |
| EndIoctl | Destroys a CFT_Ioctl object |
| GetDrvHandle | Gets the driver handle |
| CloseDrvHandle | Destroys the driver handle |
| GetDrvVersion | Gets the driver version |
| GetDrvVersionEx | Gets the hardware type and driver version |
| GetMonitorSetup | Gets the enabled/disabled monitor settings |
| GetVoltParam | Gets the voltage monitoring parameters |
| GetCurrentVolt | Gets the current value of the voltage |
| GetFanParam | Gets the parameters for monitoring the FAN |
| GetCurrentFan | Gets the current value of the FAN |
| GetTempParam | Gets the parameters for monitoring the temperature |
| GetCurrentTemp | Gets the current value of the temperature |
| SetWdtCounter | Sets the value of the watchdog timer counter |
| GetWdtCounter | Gets the watchdog timer counter |
| SetWdtDOutMask | Sets the watchdog timer counter time-out status warning mask |
| GetWdtDOutMask | Gets the watchdog timer counter time-out status warning mask |
| StartWdt | Starts the watchdog timer |
| StopWdt | Stops the watchdog timer |
| RestartWdt | Restarts the watchdog timer |
| GetWdtStatus | Gets the watchdog status |
| SetDOut | Sets the universal output |
| GetDOut | Gets the universal output |
| GetDIn | Gets the universal input |
| ClearDIn | Clears the universal input |
| SetDInMask | Sets the universal input mask |
| GetDInMask | Gets the universal input mask |
| SetResetMask | Sets the reset mask |
| GetResetMask | Gets the reset mask |
| GetEvent | Gets an error event |
| ClearEvent | Clears an error event |
| GetWdtTimeout | Gets the time-out status of the watchdog timer |
| ClearWdtTimeout | Clears the time-out status of the watchdog timer |
| SetWdtResetMask | Sets the reset mask of the watchdog timer |
| GetWdtResetMask | Gets the reset mask of the watchdog timer |
| GetSmiDrvHandle | Gets the soft mirror driver handle |
| CloseSmiDrvHandle | Destroys the soft mirror driver handle |
| GetSmiAryStatus | Gets the soft mirror array status |
| GetSmiDevStatus | Gets the soft mirror device status |

PSB_Ras.dll Functions

| Function Name | Description |
|-----------------|--------------------------|
| PsbDevWordWrite | Writes to common memory |
| PsbDevWordRead | Reads from common memory |

5.8 Visual Basic Programming Cautions

When using API-DLLs, it is important to first create the driver object and get the device handle. When you finish using the API-DLL, you will need to destroy both the device handle and the driver object. Refer to the following example when developing your programs.

MEMO

Only when using PsbDevWordWrite and PsbDevWordRead, it is not necessary to create/destroy the driver object and the device handle.

Sample Program

```
// Create the driver object
Call InitIoctl
// Get the device handle
Dim ret As Long
Dim Hndl As Long
ret = GetDrvHandle(Hndl)

.

.

.

// Output to DOUT0
Dim ret As Long
ret = SetDOut(PORT_DOUT0, OUTPUT_ON)

.

.

.

// Destroy the device handle
Dim ret As Long
ret = CloseDrvHandle()
// Destroy the driver object
Call EndIoctl
```

5.9 Visual Basic Function Specifications (Details)

InitIoctl

Call Format

Declare Sub InitIoctl Lib"PSB_Ioc.dll"

Return Value

None

Argument

None

Processing

Creates a CPSB_Ioctl object. The created object will not be released until the "EndIoctl" function is called.

Example

Call InitIoctl

EndIoctl

Call Format

Declare Sub EndIoctl Lib "PSB_Ioc.dll"()

Return Value

None

Argument

None

Processing

Destroys CPSB_Ioctl object.

Example

CallEndIoctl

GetDrvHandle

Call Format

Declare Function GetDrvHandle Lib "PSB_Ioc.dll" (ByRef Hndl As Long) As Long

Return Value

0 Normal

Other than 0 Error

Argument

Hndl As Long Device driver handle (pass by reference).

Processing

Gets the device driver handle to exchange information with the device driver.

Example

Dim ret As Long

Dim hndl As Long

ret = GetDrvHandle(hndl)

MEMO

Error (Return Value : Other than 0) will result if the system monitor/RAS device driver is not operating.

CloseDrvHandle

Call Format

Declare Function CloseDrvHandle Lib "PSB_Ioc.dll" () As Long

Return Value

Other than 0 Normal

0 Error

Argument

None

Processing

Destroys the handle acquired with the "GetDrvHandle" function.

Example

Dim ret As Long

ret = CloseDrvHandle()

GetDrvVersion

Call Format

Declare Function GetDrvVersion Lib "PSB_Ioc.dll" (ByRef Major As Long, ByRef Minor As Long) As Long

Return Value

Other than 0 Normal

0 Error

Argument

Major As Long Version Data (pass by reference)

Minor As Long Version Data (pass by reference)

Processing

Gets the driver version.

Example

Dim ret As Long

Dim Major As Long

Dim Minor As Long

ret = GetDrvVersion(Major, Minor)

MEMO

For Example, if the version is 1.00, then you will get

Major : 1 (Decimal)

Minor : 00 (Decimal).

GetDrvVersionEx

Call Format

Daclare Function GetDrvVersionEx Lib "PSB_Ioc.dll" (ByRef Product As Long, ByRef Major As Long, ByRef Minor As Long) As Long

Return Value

Other than 0 Normal

0 Error

Argument

Product As Long Hardware Type (pass by reference)

Major As Long Version Data (pass by reference)

Minor As Long Version Data (pass by reference)

Processing

Gets the hardware type and driver version.

Example

Dim ret As Long

Dim Product As Long

Dim Major As Long

Dim Minor As Long

ret = GetDrvVersionEx(Product, Major, Minor)

MEMO

For example, if the H/W type is PS-2000B and the version is 1.00, then you will get

Product : 1 (Decimal)

Major : 1 (Decimal)

Minor : 00 (Decimal).

GetMonitorSetup

Call Format

Declare Function GetMonitorSetup Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Setup As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | Parameters (pass by value) | |
|------------------|------------------------------|--------------------|
| Selector As Long | MONITOR_VOLT_CPU | CPU voltage |
| | MONITOR_VOLT_P33 | +3.3V |
| | MONITOR_VOLT_P50 | +5.0V |
| | MONITOR_VOLT_P12 | +12V |
| | MONITOR_VOLT_M12 | -12V |
| | MONITOR_VOLT_VIT | CPU voltage2 |
| | MONITOR_TEMP_SYSTEM | System temperature |
| | MONITOR_TEMP_CPU | CPU temperature |
| | MONITOR_FAN_CPU | CPU fan |
| | MONITOR_FAN_POWER | POWER fan |
| Setup As Long | Get data (pass by reference) | |
| | 0 : Disable | |
| | 1 : Enable | |

Processing

Gets the current enabled/disabled monitor status.

Example

```
Dim ret As Long
Dim Setup As Long
' Get the setup status of the CPU core voltage.
ret = GetMonitorSetup(MONITOR_VOLT_CPU, Setup)
```

GetVoltParam

Call Format

Declare Function GetVoltParam Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef ULimit As Long, ByRef LLimit As Long)

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | | |
|------------------|---|--------------|
| Selector As Long | Parameters (pass by value) | |
| | MONITOR_VOLT_CPU | CPU voltage |
| | MONITOR_VOLT_P33 | +3.3V |
| | MONITOR_VOLT_P50 | +5.0V |
| | MONITOR_VOLT_P12 | +12V |
| | MONITOR_VOLT_M12 | -12V |
| | MONITOR_VOLT_VIT | CPU voltage2 |
| ULimit As Long | Voltage value upper-limit (Unit: mV)(pass by reference) | |
| LLimit As Long | Voltage value lower-limit (Unit: mV)(pass by reference) | |

Processing

Gets the voltage monitoring parameter.

Example

```
Dim ret As Long
Dim ULimit As Long
Dim LLimit As Long
' Get the upper/lower limit of the CPU core voltage value
ret = GetVoltParam(MONITOR_VOLT_CPU, ULimit, LLimit)
```

MEMO

The data received from this function is in mV units.

Perform the following conversion for use in (Volt) units:

$$\text{Data in Volt unit} = \text{Data in mV unit} / 1000$$

GetCurrentVolt

Call Format

Declare Function GetCurrentVolt Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Data As Long) As Long

Return Value

Other than 0 Normal
0 Error

Argument

| | |
|------------------|------------------------------------|
| Selector As Long | Parameters (pass by value) |
| | MONITOR_VOLT_CPU CPU voltage |
| | MONITOR_VOLT_P33 +3.3V |
| | MONITOR_VOLT_P50 +5.0V |
| | MONITOR_VOLT_P12 +12V |
| | MONITOR_VOLT_M12 -12V |
| | MONITOR_VOLT_VIT CPU voltage2 |

Data As Long Voltage value (Unit: mV) (pass by reference)

Processing

Gets the current voltage value.

Example

```
Dim ret As Long
Dim Data As Long
' Get the CPU core voltage value.
ret = GetCurrentVolt(MONITOR_VOLT_CPU, Data)
```

MEMO

The data received from this function is in mV units.

Perform the following conversion for use in (Volt) units:

$$\text{Data in Volt unit} = \text{Data in mV unit} / 1000$$

GetFanParam

Call Format

Declare Function GetFanParam Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef LLimit As Long) As Long

Return Value

Other than 0 Normal
0 Error

Argument

| | |
|------------------|----------------------------------|
| Selector As Long | Parameters (pass by value) |
| | MONITOR_FAN_CPU CPU fan |
| | MONITOR_FAN_POWER POWER fan |

LLimit As Long FAN revolution lower-limit value (Unit: RPM) (pass by reference)
(RPM : Revolutions per minute)

Processing

Gets the parameter for monitoring the FAN.

Example

```
Dim ret As Long
Dim LLimit As Long
' Gets the CPU FAN lower-limit rpm value.
ret = GetFanParam(MONITOR_FAN_CPU, LLimit)
```

GetCurrentFan

Call Format

Declare Function GetCurrentFan Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Data As Long) As Long

Return Value

Other than 0 Normal
0 Error

Argument

| | |
|------------------|--|
| Selector As Long | Parameters (pass by value) |
| | MONITOR_FAN_CPU CPU fan |
| | MONITOR_FAN_POWER POWER fan |
| Data As Long | FAN revolution value (Unit: RPM) (pass by reference) (RPM : Revolutions per minute) |

Processing

Gets the current FAN rpm.

Example

```
Dim ret As Long
Dim Data As Long
' Gets the RPM of the CPU FAN.
ret = GetCurrentFan(MONITOR_FAN_CPU, Data)
```

GetTempParam

Call Format

Declare Function GetTempParam Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef ULimit As Long) As Long

Return Value

Other than 0 Normal
0 Error

Argument

| | |
|------------------|---|
| Selector As Long | Parameters (pass by value) |
| | MONITOR_TEMP_CPU CPU temperature |
| | MONITOR_TEMP_SYSTEM System temperature |
| ULimit As Long | Temperature upper-limit (Unit °C) (pass by reference) |

Processing

Gets the parameter for monitoring the temperature.

Example

```
Dim ret As Long
Dim ULimit As Long
' Gets the upper-limit of CPU temperature.
ret = GetTempParam(MONITOR_TEMP_CPU, ULimit)
```

GetCurrentTemp

Call Format

Declare Function GetCurrentTemp Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Data As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|------------------|--|
| Selector As Long | Parameters (pass by value) |
| | MONITOR_TEMP_CPU CPU temperature |
| | MONITOR_TEMP_SYSTEM System temperature |

| | |
|--------------|--|
| Data As Long | Temperature value (Unit: °C) (pass by reference) |
|--------------|--|

Processing

Gets the current temperature value.

Example

```
Dim ret As Long
Dim Data As Long
```

```
' Get the current value of CPU temperature.
```

```
ret = GetCurrentTemp(MONITOR_TEMP_CPU, Data)
```

SetWdtCounter

Call Format

Declare Function SetWdtCounter Lib "PSB_Ioc.dll" (ByVal Counter As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|-----------------|--|
| Counter As Long | The initial counter value of the watchdog timer (5 to 255) (Unit: second) (pass by value) |
|-----------------|--|

Processing

Sets the initial counter value for the watchdog timer.

Example

```
Dim ret As Long
```

```
' Sets the initial counter value for the watchdog timer to 10 seconds.
```

```
ret = SetWdtCounter(10)
```

GetWdtCounter

Call Format

Declare Function GetWdtCounter Lib "PSB_Ioc.dll" (ByRef Counter As Long) As Long

Return Value

Other than 0 Normal

0 Error

Argument

Counter As Long The initial couter value of the watchdog timer (pass by value)

Processing

Gets the initial counter value of the current watchdog timer.

Example

Dim ret As Long

Dim Counter As Long

' Gets the initial counter value of the current watchdog timer.

ret = GetWdtCounter(Counter)

SetWdtDOutMask

Call Format

Declare Function SetWdtDOutMask Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByVal Mask As Long)

Return Value

Other than 0 Normal

0 Error

Argument

Selector As Long Setting Item (pass by value)

PORT_DOUT0 DOUT0

PORT_DOUT1 DOUT1

PORT_DOUT2 DOUT2

PORT_DOUT3 DOUT3

Mask As Long Mask Information (pass by value)

MASK_OFF Masking disabled

MASK_ON Masking enabled

Processing

Sets the mask for the RAS port used for Watchdog Timer Timeout output.

Example

Dim ret As Long

' Mask the RAS port's DOUT0.

ret = SetWdtDOutMask(PORT_DOUT0, MASK_ON)

GetWdtDOutMask

Call Format

Declare Function GetWdtDOutMask Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Mask As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|------------------|---|
| Selector As Long | Setting Item (pass by value) |
| | PORT_DOUT0 DOUT0 |
| | PORT_DOUT1 DOUT1 |
| | PORT_DOUT2 DOUT2 |
| | PORT_DOUT3 DOUT3 |
| Mask As Long | Masking Information (pass by reference) |
| | MASK_OFF Masking disabled |
| | MASK_ON Masking enabled |

Processing

Gets the WDT time out warning output of the RAS port's mask data.

Example

```
Dim ret As Long
Dim Mask As Long
' Gets DOUT0 of RAS port mask data.
ret = GetWdtDOutMask(PORT_DOUT0, Mask)
```

StartWdt

Call Format

Declare Function StartWdt Lib "PSB_Ioc.dll"() As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

None

Processing

Starts the WDT countdown.

Example

```
Dim ret As Long
ret = StartWdt()
```

StopWdt

Call Format

Declare Function StopWdt Lib "PSB_Ioc.dll"() As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

None

Processing

Stops the WDT coutdown.

Example

Dim ret As Long

ret = StopWdt()

RestartWdt

Call Format

Declare Function RestartWdt Lib "PSB_Ioc.dll"() As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

None

Processing

This feature resets the Watchdog timer that is currently counting (down) to its initial value, and restarts the countdown.

Example

Dim ret As Long

ret = RestartWdt()

MEMO

RestartWdt can only be used after the StartWdt countdown has started. If RestartWdt is used after the timeout, it should be after ClearWdtTimeout has used to clear the timeout condition and after StartWdt has started the countdown.

GetWdtStatus

Call Format

Declare Function GetWdtStatus Lib "PSB_Ioc.dll" (ByRef RunFlag As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|-----------------|--|
| RunFlag As Long | Operation Status of the watchdog timer (pass by reference) |
| | WATCHDOG_STOP Stopped |
| | WATCHDOG_COUNTDOWN Counting down |

Processing

Gets the operation status of the watchdog timer.

Example

```
Dim ret As Long
Dim RunFlag As Long
ret = GetWdtStatus(RunFlag)
```

SetDOut

Call Format

Declare Function SetDOut Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByVal Dout As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|------------------|-------------------------------|
| Selector As Long | Setting Item (pass by value) |
| | PORT_DOUT0 DOUT0 |
| | PORT_DOUT1 DOUT1 |
| | PORT_DOUT2 DOUT2 |
| | PORT_DOUT3 DOUT3 |
| Dout As Long | Output Status (pass by value) |
| | OUTPUT_OFF Output OFF |
| | OUTPUT_ON Output ON |

Processing

Sets the Common Output port (DOUT) output data.

Example

```
Dim ret As Long
ret = SetDOut(PORT_DOUT0, OUTPUT_ON)
```

GetDOut

Call Format

Declare Function GetDOut Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Dout As Long) As Long

Return Value

Other than 0 Normal
0 Error

Argument

| | |
|------------------|-----------------------------------|
| Selector As Long | Setting Item (pass by value) |
| | PORT_DOUT0 DOUT0 |
| | PORT_DOUT1 DOUT1 |
| | PORT_DOUT2 DOUT2 |
| | PORT_DOUT3 DOUT3 |
| Dout As Long | Output Status (pass by reference) |
| | OUTPUT_OFF Output OFF |
| | OUTPUT_ON Output ON |

Processing

Gets the Common Output port (DOUT) output data.

Example

```
Dim ret As Long
Dim Dout As Long
ret=GetDOut(PORT_DOUT0,Dout)
```

GetDIn

Call Format

Declare Function GetDIn Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Din As Long) As Long

Return Value

Other than 0 Normal
0 Error

Argument

| | |
|------------------|----------------------------------|
| Selector As Long | Setting Item (pass by value) |
| | PORT_DIN0 DIN0 |
| | PORT_DIN1 DIN1 |
| | PORT_DIN2 DIN2 |
| | PORT_DIN3 DIN3 |
| Din As Long | Input Status (pass by reference) |
| | INPUT_OFF Input OFF |
| | INPUT_ON Input ON |

Processing

Gets the Input status of the designated port (DIN).

Example

```
Dim ret As Long
Dim Din As Long
ret=GetDIn(PORT_DIN0,Din)
```

ClearDIn

Call Format

Declare Function ClearDIn Lib "PSB_Ioc.dll" (ByVal Selector As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|------------------|------------------------------|
| Selector As Long | Setting Item (pass by value) |
| | PORt_DIN0 DIN0 |
| | PORt_DIN1 DIN1 |
| | PORt_DIN2 DIN2 |
| | PORt_DIN3 DIN3 |

Processing

Releases the Common Input port (DIN) input status.

Example

```
Dim ret As Long
ret = ClearDIn(PORT_DIN0)
```

SetDInMask

Call Format

Declare Function SetDInMask Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByVal Mask As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|------------------|-------------------------------------|
| Selector As Long | Setting Item (pass by value) |
| | PORt_DIN0 DIN0 |
| | PORt_DIN1 DIN1 |
| | PORt_DIN2 DIN2 |
| | PORt_DIN3 DIN3 |
| Mask As Long | Masking Information (pass by value) |
| | MASK_ON Masking enabled |
| | MASK_OFF Masking disabled |

Processing

Sets the Common Input Port (DIN) input status.

Example

```
Dim ret As Long
ret = SetDInMask(PORT_DIN0, MASK_OFF)
```

GetDInMask

Call Format

Declare Function GetDInMask Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Mask As Long) As Long

Return Value

Other than 0 Normal

0 Error

Argument

Selector As Long Setting Item (pass by value)

PORT_DIN0 DIN0

PORT_DIN1 DIN1

PORT_DIN2 DIN2

PORT_DIN3 DIN3

Mask As Long Masking Information (pass by reference)

MASK_ON Masking enabled

MASK_OFF Masking disabled

Processing

Gets the masking information of the subject ports (DIN).

Example

Dim ret As Long

Dim Mask As Long

ret = GetDInMask(PORT_DIN0, Mask)

SetResetMask

Call Format

Declare Function SetResetMask Lib "PSB_Ioc.dll" (ByVal Mask As Long) As Long

Return Value

Other than 0 Normal

0 Error

Argument

Mask As Long Masking Information (pass by value)

MASK_ON Masking enabled

MASK_OFF Masking disabled

Processing

Sets the reset port's mask data.

Example

Dim ret As Long

ret = SetResetMask(MASK_OFF)

GetResetMask

Call Format

Declare Function GetResetMask Lib "PSB_Ioc.dll" (ByRef Mask As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|--------------|---|
| Mask As Long | Masking Information (pass by reference) |
| MASK_ON | Masking enabled |
| MASK_OFF | Masking disabled |

Processing

Gets the current reset mask information.

Example

```
Dim ret As Long
Dim Mask As Long
ret = GetResetMask(Mask)
```

GetEvent

Call Format

Declare Function GetEvent Lib "PSB_Ioc.dll" (ByVal Selector As Long, ByRef Rasevent As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | | |
|------------------|--------------------------------------|--------------------|
| Selector As Long | Parameters (pass by value) | |
| | EVENT_VOLT_CPU | CPU voltage |
| | EVENT_VOLT_P33 | +3.3V |
| | EVENT_VOLT_P50 | +5V |
| | EVENT_VOLT_P12 | +12V |
| | EVENT_VOLT_M12 | -12V |
| | EVENT_VOLT_VIT | CPU voltage2 |
| | EVENT_FAN_CPU | CPU fan |
| | EVENT_FAN_POWER | POWER fan |
| | EVENT_TEMP_SYSTEM | System temperature |
| | EVENT_TEMP_CPU | CPU temperature |
| | EVENT_DIN0 | DIN0 |
| | EVENT_DIN1 | DIN1 |
| | EVENT_DIN2 | DIN2 |
| | EVENT_DIN3 | DIN3 |
| | EVENT_WDT_TIMEOUT | Watchdog Timer |
| Rasevent As Long | Error event data (pass by reference) | |
| | ERROR_EVENT_ON | Error event |
| | ERROR_EVENT_OFF | No Error event |

Processing

Gets the event information.

Example

```
Dim ret As Long
Dim Rasevent As Long
ret = GetEvent(EVENT_DIN0, Rasevent)
```

ClearEvent

Call Format

Declare Function ClearEvent Lib “PSB_Ioc.dll” (ByVal Selector As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| Selector As Long | Parameters (pass by value) |
|-------------------|----------------------------|
| EVENT_VOLT_CPU | CPU voltage |
| EVENT_VOLT_P33 | +3.3V |
| EVENT_VOLT_P50 | +5V |
| EVENT_VOLT_P12 | +12V |
| EVENT_VOLT_M12 | -12V |
| EVENT_VOLT_VIT | CPU voltage2 |
| EVENT_FAN_CPU | CPU fan |
| EVENT_FAN_POWER | POWER fan |
| EVENT_TEMP_SYSTEM | System temperature |
| EVENT_TEMP_CPU | CPU temperature |
| EVENT_DIN0 | DIN0 |
| EVENT_DIN1 | DIN1 |
| EVENT_DIN2 | DIN2 |
| EVENT_DIN3 | DIN3 |
| EVENT_WDT_TIMEOUT | Watchdog Timer |

Processing

Cancels the error event.

Example

```
Dim ret As Long
ret = ClearEvent(EVENT_DIN0)
```

GetWdtTimeout

Call Format

Declare Function GetWdtTimeout Lib “PSB_Ioc.dll” (ByRef Timebuf As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| Timebuf As Long | WDT timeout status (pass by reference) |
|-----------------|--|
| TIMEOUT_OK | Timeout has not occurred |
| TIMEOUT_ERR | Timeout has occurred |

Processing

Gets the watchdog timeout status.

Example

```
Dim ret As Long
Dim Timebuf As Long
ret = GetWdtTimeout(Timebuf)
```

ClearWdtTimeout

Call Format

Declare Funciton ClearWdtTimeout Lib “PSB_Ioc.dll”() As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

None

Processing

Clears the watchdog timeout status.

Example

```
Dim ret As Long
ret = ClearWdtTimeout()
```

SetWdtResetMask

Call Format

Declare Function SetWdtResetMask Lib “PSB_Ioc.dll” (ByVal Mask As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|--------------|-------------------------------------|
| Mask As Long | Masking information (pass by value) |
| | MASK_OFF Masking disabled |
| | MASK_ON Masking enabled |

Processing

Sets the H/W reset mask for the WDT timeout.

Example

```
Dim ret As Long
ret = SetWdtResetMask(MASK_ON)
```

GetWdtResetMask

Call Format

Declare Function GetWdtResetMask Lib “PSB_Ioc.dll” (ByRef Mask As Long) As Long

Return Value

| | |
|--------------|--------|
| Other than 0 | Normal |
| 0 | Error |

Argument

| | |
|--------------|---|
| Mask As Long | Masking Information (pass by reference) |
| | MASK_OFF Masking disabled |
| | MASK_ON Masking enabled |

Processing

Gets the WDT timeout's H/W reset mask data.

Example

```
Dim ret As Long
Dim Mask As Long
ret = GetWdtResetMask(Mask)
```

PsbDevWordWrite

Call Format

Declare Function PsbDevWordWrite Lib "PSB_Ras.dll"

(ByVal Addr As Long, ByVal wData As Long) As Long

Return Value

0 Normal

Other than 0 Error

Argument

Addr As Long Write memory word address.

wData As Long Write data (0 to 65535)

Processing

Writes to common memory.

Example

' Writes data 255 to address 255.

Dim ret As Long

ret = PsbDevWordWrite(255, 255)

PsbDevWordRead

Call Format

Declare Function PsbDevWordRead Lib "PSB_Ras.dll"

(ByVal Addr As Long, ByRef wData As Long) As Long

Return Value

0 Normal

Other than 0 Error

Argument

Addr As Long Read memory word address

wData As Long Read data (0 to 65535)

Processing

Reads from common memory.

Example

' Reads address 255's data.

Dim ret As Long

Dim wData As Long

ret = PsbDevWordRead(255, wData)

GetSmiDrvHandle

Call Format

Declare Function GetSmiDrvHandle Lib "PSB_Ioc.dll" () AS Long

Return Value

0 Normal

Other than 0 Error

Argument

None

Processing

Gets the soft mirror device driver handle.

Example

Dim ret As Long

ret=GetSmiDrvHandle()

MEMO Error (Return Value : Other than 0) will result if the soft mirror device driver is not operating.

CloseSmiDrvHandle

Call Format

Declare Function CloseSmiDrvHandle Lib "Psb_Ioc.dll" () As Long

Return Value

Other than 0 Normal

0 Error

Argument

None

Processing

Destroys the soft mirror device driver handle.

Example

Dim ret As Long

ret=CloseSmiDrvHandle()

GetSmiAryStatus

Call Format

Declare Function GetSmiAryStatus Lib "Psb_Ioc.dll"

Return Value

Other than 0 Normal

0 Error

Argument

Status As Long soft mirror's mirroring status (pass by reference)

Processing

Get the soft mirror's mirroring status.

Example

Dim ret As Long

Dim Status As Long

ret = GetSmiAryStatus(Status)

GetSmiDevStatus

Call Format

Declare Function GetSmiDevStatus Lib "Psb_Loc.dll"

(ByValID As Long, ByRef Type As Long, By Ref Status As Long) As Long

Return Value

Other than 0 Normal

0 Error

Argument

ID As Long Device ID (pass by value)

0 : Master HDD

1 : Slave HDD

Type As Long Device Type (pass by reference)

ATADEVICE ATA device

ATAPIDEVICE CD-ROM

NODEVICE Not connected

Status As Long Device Status (pass by reference)

DEVSTAT_GOOD Normal

DEVSTAT_NOTEXIST Not connected

DEVSTAT_BROKEN Broken

Processing

Gets the soft mirror device status.

Example

Dim ret As Long

Dim Type As Long

Dim Status As Long

ret = GetSmiDrvStatus(0, Type, Status)